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```
% Coast Down Data Analysis
```

```
close all
clear
clc

load dlp8-B.mat
rho=1.1839; % kg/m^3
N=319.193*9.8; % N
A=1.08; % m^2
```

Finding velocity indices

```
close all

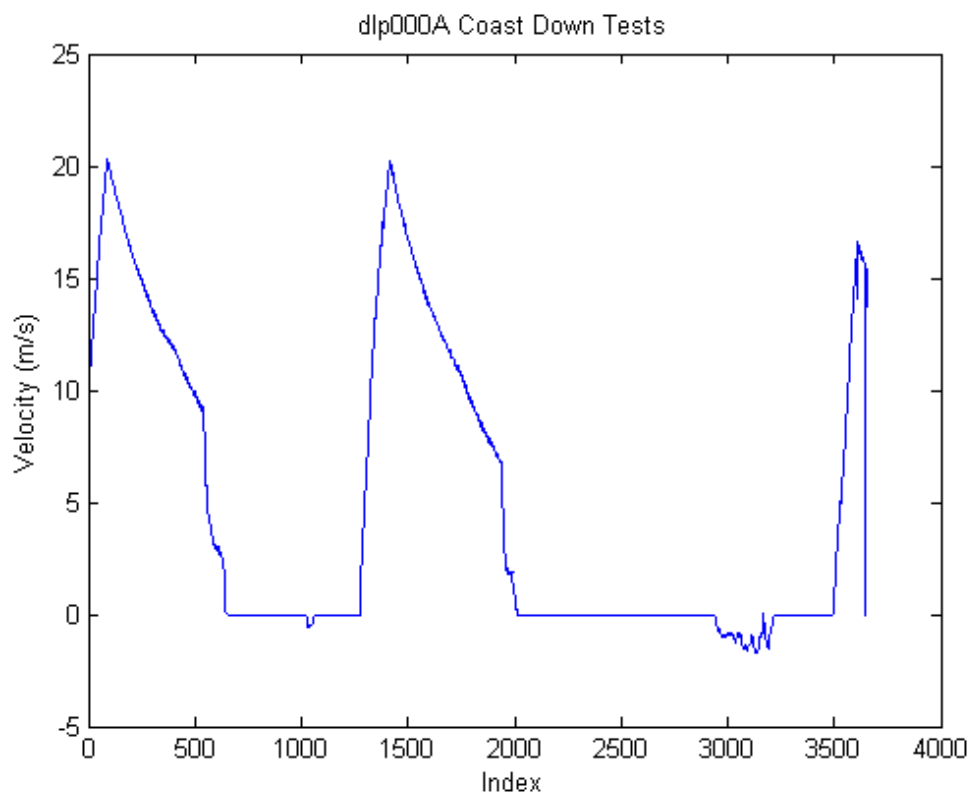
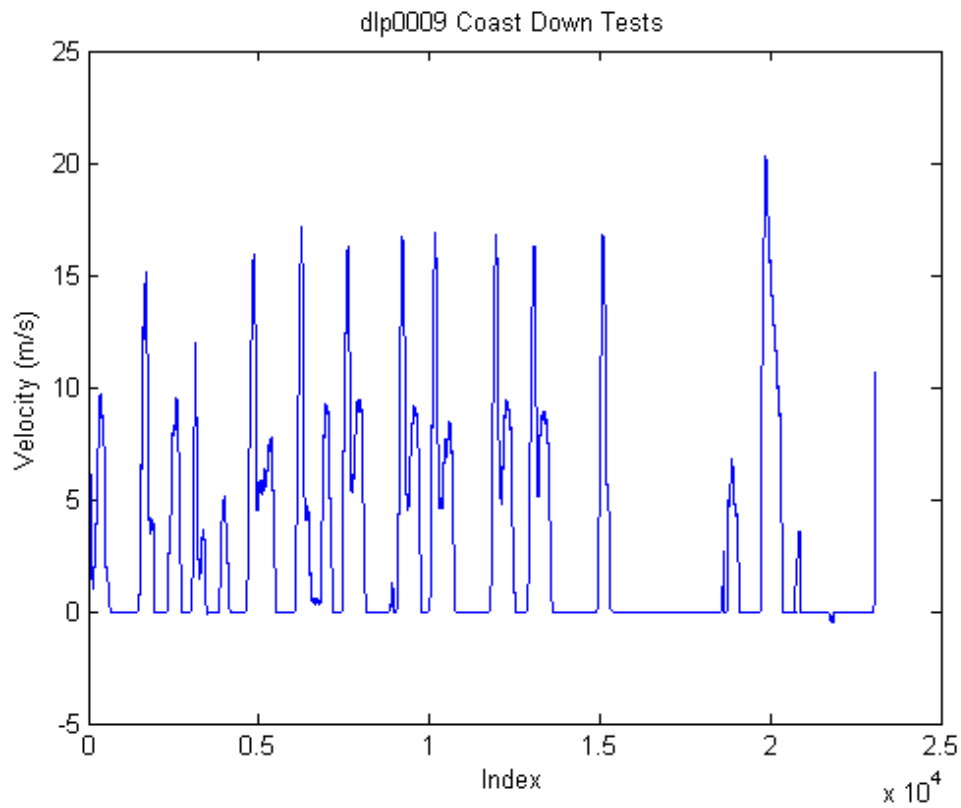
index9=0;
for k=1:size(dlp0009,2)
    if strcmp(dlp0009(k).desc,' Vehicle Velocity m/s Vehicle velocity in metres / second.')
        index9=k;
    end
end

indexA=0;
for k=1:size(dlp000A,2)
    if strcmp(dlp000A(k).desc,' Vehicle Velocity m/s Vehicle velocity in metres / second.')
        indexA=k;
    end
end
```

Plotting data

```
figure
plot(dlp0009(index9).values)
title('dlp0009 Coast Down Tests')
xlabel('Index')
ylabel('Velocity (m/s)')

figure
plot(dlp000A(indexA).values)
title('dlp000A Coast Down Tests')
xlabel('Index')
ylabel('Velocity (m/s)')
```



Isolating tests

```
close all
```

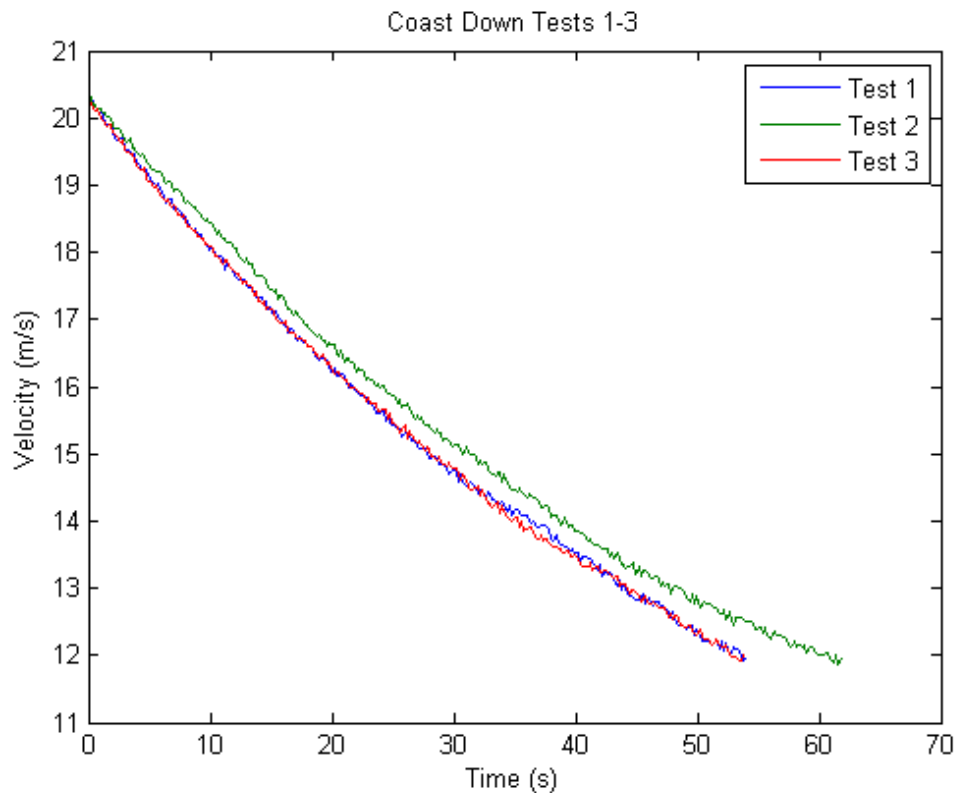
```
tin1=19870:20140;
```

```
tin2=89:398;
```

```

tin3=1415:1684;
figure
plot(dlp0009(index9).times(tin1)-dlp0009(index9).times(tin1(1)),...
     dlp0009(index9).values(tin1),...
     dlp000A(indexA).times(tin2)-dlp000A(indexA).times(tin2(1)),...
     dlp000A(indexA).values(tin2),...
     dlp000A(indexA).times(tin3)-dlp000A(indexA).times(tin3(1)),...
     dlp000A(indexA).values(tin3))
title('Coast Down Tests 1-3')
xlabel('Time (s)')
ylabel('Velocity (m/s)')
legend('Test 1','Test 2','Test 3')

```



Creating time and velocity vectors

```

t1=dlp0009(index9).times(tin1)-dlp0009(index9).times(tin1(1));
v1=dlp0009(index9).values(tin1);

t2=dlp000A(indexA).times(tin2)-dlp000A(indexA).times(tin2(1));
v2=dlp000A(indexA).values(tin2);

t3=dlp000A(indexA).times(tin3)-dlp000A(indexA).times(tin3(1));
v3=dlp000A(indexA).values(tin3);

```

Test 1 Coefficient Calculations

```

% close all

% Cubic regression of velocity curve (coefficients stored in "vlfits")
vlfits=polyfit(t1,v1,3);
vlanon=@(t) vlfits(1).*t.^3+vlfits(2).*t.^2+vlfits(3).*t+vlfits(4);

% Plot to verify regression
figure
plot(t1,v1,t1,vlanon(t1))

```

```

title('Velocity Test 1 and cubic fit')
xlabel('Time (s)')
ylabel('Velocity (m/s)')
legend('Raw velocity data','Fitted curve')

% Differentiate v(t) curve to get acceleration
alfits=[vlfits(1)*3 vlfits(2)*2 vlfits(3)];
alanon=@(t) alfits(1).*t.^2+alfits(2).*t+alfits(3);

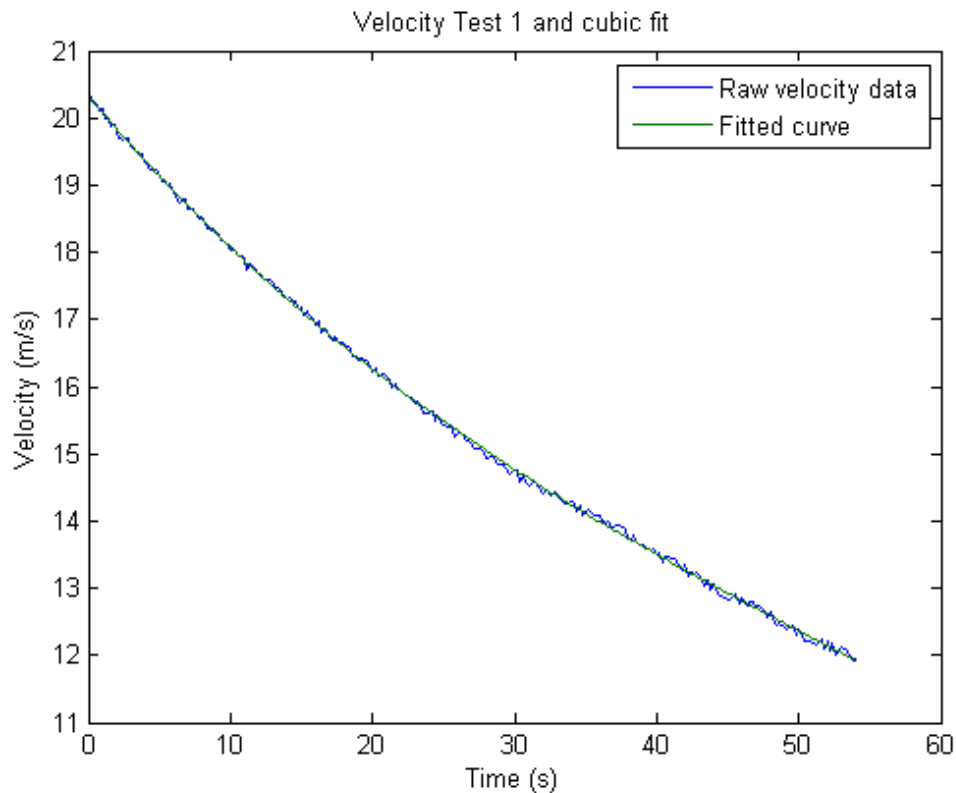
% Plot acceleration to verify
figure
plot(t1,alanon(t1))
title('Acceleration Test 1')
xlabel('Time (s)')
ylabel('Acceleration (m/s^2)')

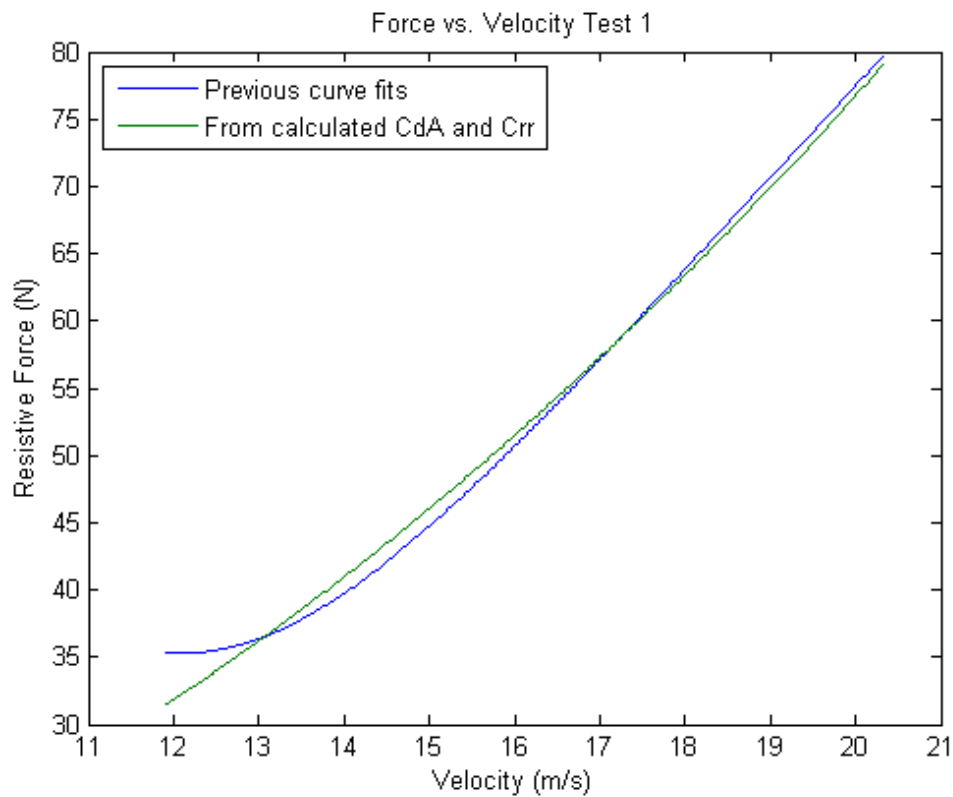
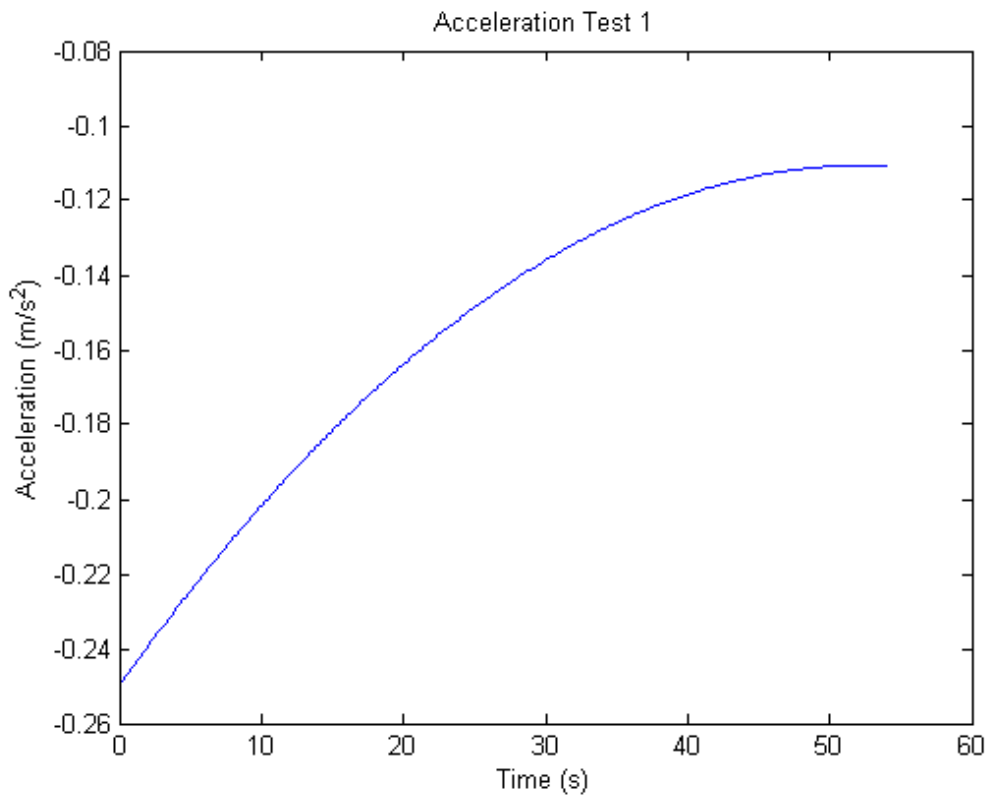
% F=ma
flanon=@(t) -319.193.*alanon(t);

soll=[vlanon(t1).^2 ones(length(t1),1)]\flanon(t1)';
CdA1=soll(1)*2/rho;
Crr1=soll(2)/N;

figure
plot(vlanon(t1),flanon(t1),...
vlanon(t1),0.5*rho*CdA1.*vlanon(t1).^2+Crr1*N)
title('Force vs. Velocity Test 1')
xlabel('Velocity (m/s)')
ylabel('Resistive Force (N)')
legend('Previous curve fits','From calculated CdA and Crr','Location','NorthWest')

```





Test 2 Coefficient Calculations

```
% close all
```

```
% Cubic regression of velocity curve (coefficients stored in "v2fits")  
v2fits=polyfit(t2,v2,3);
```

```

v2anon=@(t) v2fits(1).*t.^3+v2fits(2).*t.^2+v2fits(3).*t+v2fits(4);

% Plot to verify regression
figure
plot(t2,v2,t2,v2anon(t2))
    title('Velocity Test 2 and cubic fit')
    xlabel('Time (s)')
    ylabel('Velocity (m/s)')
    legend('Raw velocity data','Fitted curve')

% Differentiate v(t) curve to get acceleration
a2fits=[v2fits(1)*3 v2fits(2)*2 v2fits(3)];
a2anon=@(t) a2fits(1).*t.^2+a2fits(2).*t+a2fits(3);

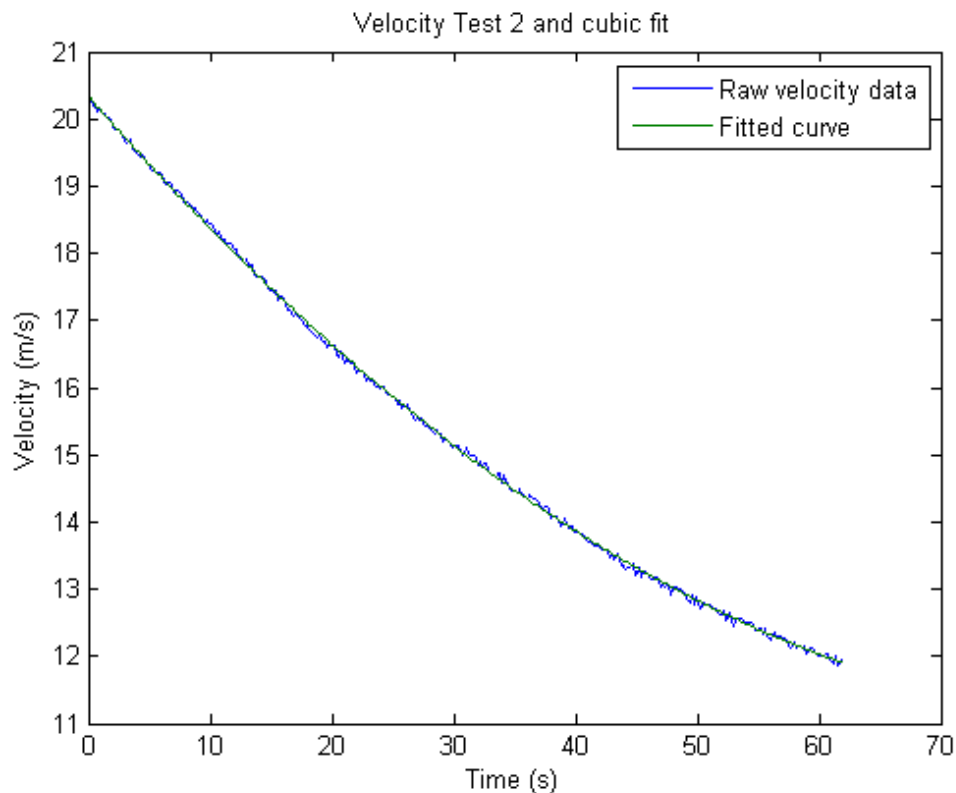
% Plot acceleration to verify
figure
plot(t2,a2anon(t2))
    title('Acceleration Test 2')
    xlabel('Time (s)')
    ylabel('Acceleration (m/s^2)')

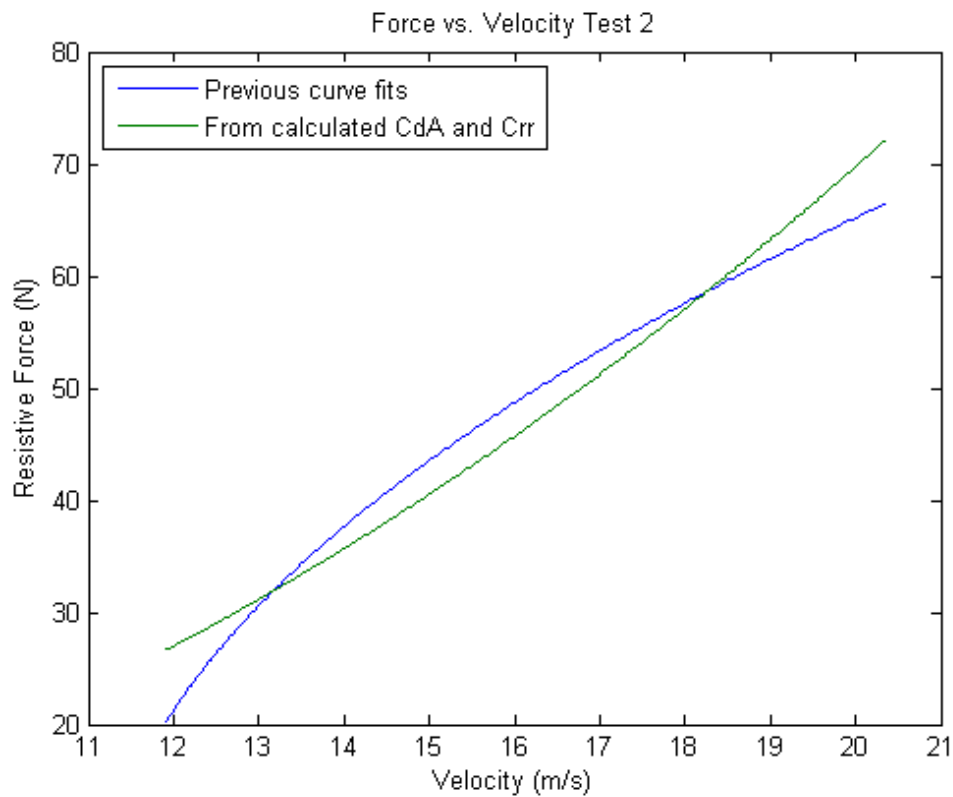
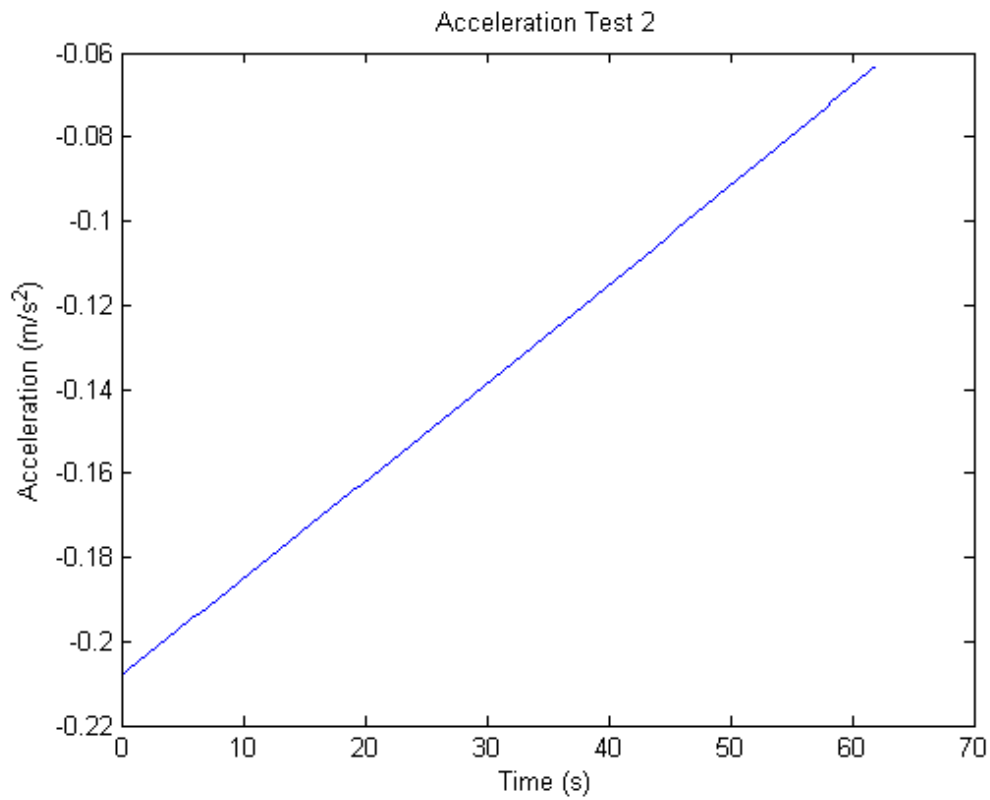
% F=ma
f2anon=@(t) -319.193.*a2anon(t);

sol2=[v2anon(t2).^2 ones(length(t2),1)]\f2anon(t2)';
CdA2=sol2(1)*2/rho;
Crr2=sol2(2)/N;

figure
plot(v2anon(t2),f2anon(t2),...
    v2anon(t2),0.5*rho*CdA2.*v2anon(t2).^2+Crr2*N)
    title('Force vs. Velocity Test 2')
    xlabel('Velocity (m/s)')
    ylabel('Resistive Force (N)')
    legend('Previous curve fits','From calculated CdA and Crr','Location','NorthWest')

```





Test 3 Coefficient Calculations

```
% close all
```

```
% Cubic regression of velocity curve (coefficients stored in "v3fits")
v3fits=polyfit(t3,v3,3);
```

```

v3anon=@(t) v3fits(1).*t.^3+v3fits(2).*t.^2+v3fits(3).*t+v3fits(4);

% Plot to verify regression
figure
plot(t3,v3,t3,v3anon(t3))
    title('Velocity Test 3 and cubic fit')
    xlabel('Time (s)')
    ylabel('Velocity (m/s)')
    legend('Raw velocity data','Fitted curve')

% Differentiate v(t) curve to get acceleration
a3fits=[v3fits(1)*3 v3fits(2)*2 v3fits(3)];
a3anon=@(t) a3fits(1).*t.^2+a3fits(2).*t+a3fits(3);

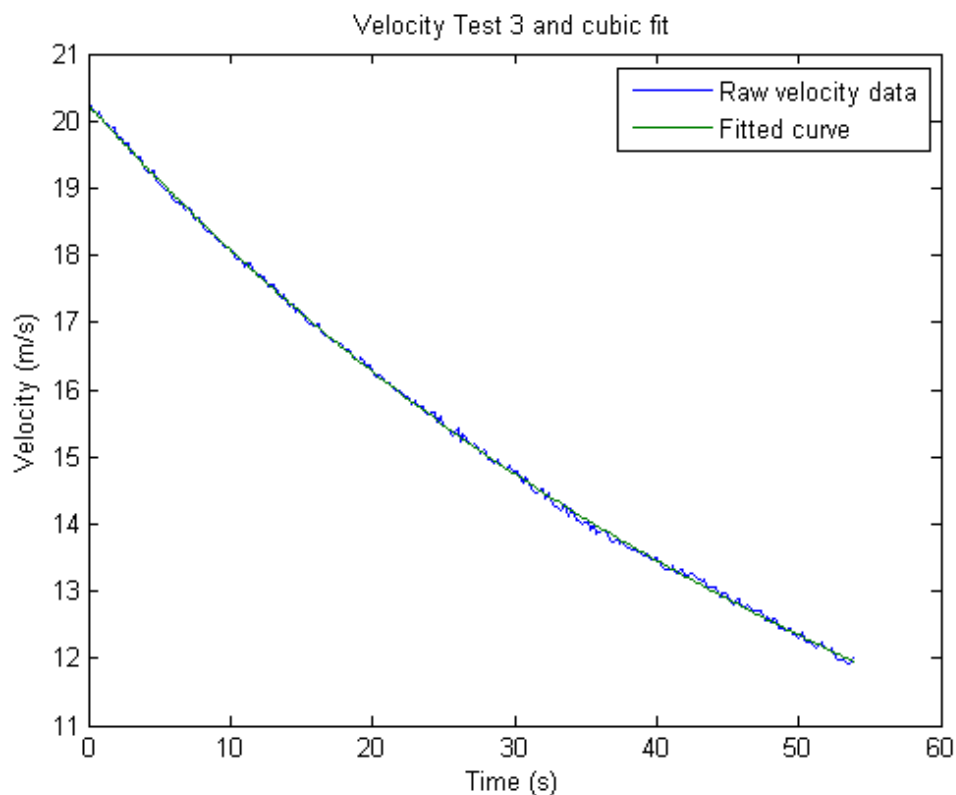
% Plot acceleration to verify
figure
plot(t3,a3anon(t3))
    title('Acceleration Test 3')
    xlabel('Time (s)')
    ylabel('Acceleration (m/s^2)')

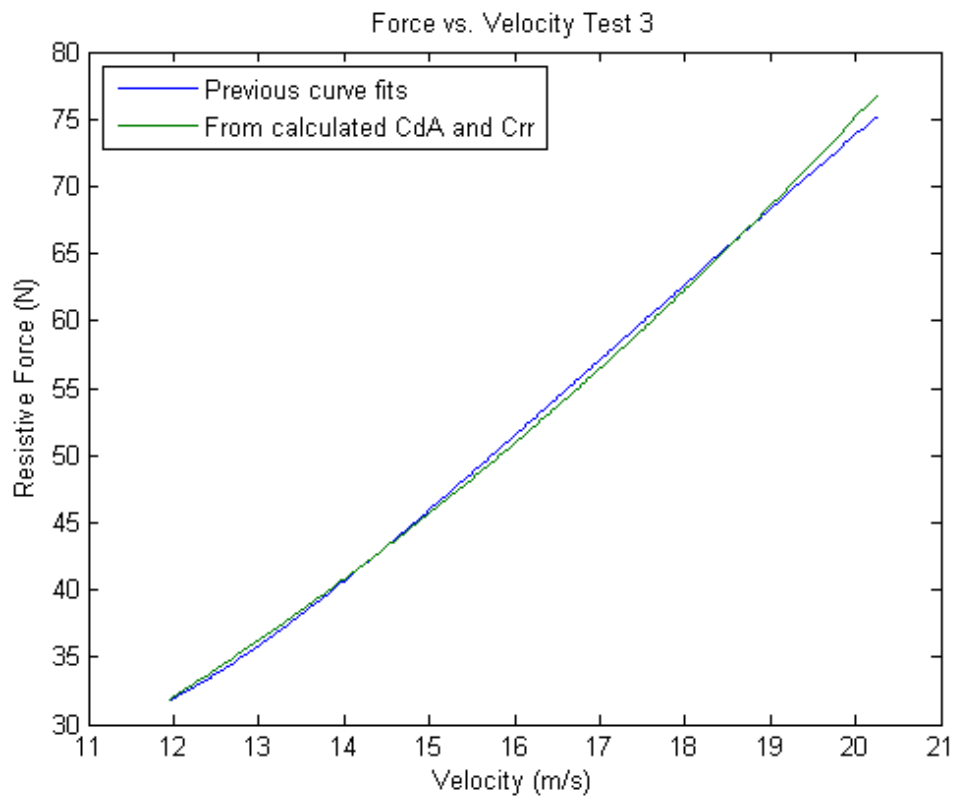
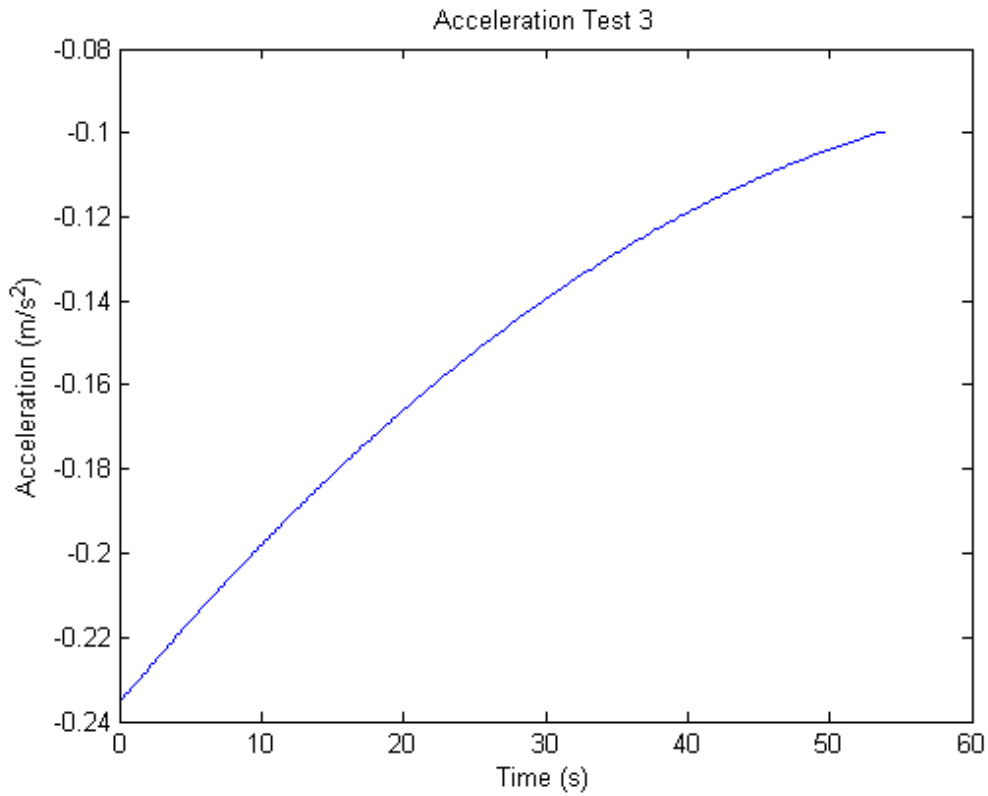
% F=ma
f3anon=@(t) -319.193.*a3anon(t);

sol3=[v3anon(t3).^2 ones(length(t3),1)]\f3anon(t3)';
CdA3=sol3(1)*2/rho;
Crr3=sol3(2)/N;

figure
plot(v3anon(t3),f3anon(t3),...
    v3anon(t3),0.5*rho*CdA3.*v3anon(t3).^2+Crr3*N)
    title('Force vs. Velocity Test 3')
    xlabel('Velocity (m/s)')
    ylabel('Resistive Force (N)')
    legend('Previous curve fits','From calculated CdA and Crr','Location','NorthWest')

```





```

CdA=[CdA1; CdA2; CdA3] % m^2
Cd=CdA/A % arb. unit
Crr=[Crr1; Crr2; Crr3] % arb. unit
close all

```

```
CdA =  
    0.2963  
    0.2821  
    0.2842  
Cd =  
    0.2743  
    0.2612  
    0.2631  
Crr =  
    0.0021  
    0.0010  
    0.0025
```

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